

BASIC DEFINITIONS

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1. CHAPTER I

Linear Independent. A set of vectors $\{u_1, u_2, \dots, u_k\}$ are *linear independent* if the only solution to $a_1u_1 + a_2u_2 + \dots + a_ku_k = 0$ is $a_1 = a_2 = \dots = a_k = 0$.

Span Space. The *Span Space* of vectors $\{u_1, u_2, \dots, u_k\}$ is the space that contains all the linear combinations of them.

Linear Transform. A *Linear Transform* is a function $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

- (1) For any vectors u and v , $T(u) + T(v) = T(u + v)$.
- (2) For any scalar c , $T(cu) = cT(u)$

Injective and Surjective. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transform.

- (1) A linear transform T is *injective* if whenever $u \neq v$, $T(u) \neq T(v)$. Or equivalently, $T(u) = 0$ if and only if $u = 0$; i.e., the kernel space of T is $\{0\}$.
- (2) A linear transform T is *surjective* if for any vector B in \mathbb{R}^m , there exists some u in \mathbb{R}^n such that $T(u) = B$. Or equivalently, the image space of T is \mathbb{R}^m .

Kernel Space and Image Space. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transform.

- (1) The *Kernel Space* of T is the set of vectors u in \mathbb{R}^n such that $T(u) = 0$.
- (2) The *Image Space* of T is the set of vectors B in \mathbb{R}^m such that $B = T(u)$ for some u in \mathbb{R}^n .

2. CHAPTER II

Column Space. The *Column Space* of a matrix A is the space spanned by the column vectors of A .

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(Linear) Subspace. A *(Linear) Subspace* of \mathbb{R}^n is a subset H of \mathbb{R}^n such that

- (1) If u and v are in H , then $u + v$ is in H .
- (2) If u is in H , then cu is in H for any scalar c .

Basis of a Subspace. The *Basis* of a linear subspace H is a set of vectors \mathcal{B} such that

- (1) The vectors in \mathcal{B} span H .
- (2) The vectors in \mathcal{B} are linear independent.

Dimension of a Linear subspace. The *dimension* of a linear subspace is the number of vectors in any of its basis.

Rank of a Matrix. The *Rank* of a matrix is the dimension of the column space of A . Or equivalently, the number of linear independent vectors among the column vectors.

3. FINAL EXAM

The definitions of the final exam will come from the following.

- (1) λ is an eigenvalue of A .
- (2) u is an eigenvector of A .
- (3) Characteristic polynomial of a matrix A .
- (4) A is diagonalizable.
- (5) The dot product of u and v . The length of u . The distance between u and v .
- (6) The orthogonal projection of u on a subspace H .
- (7) A set of vectors is orthogonal/orthonormal.
- (8) Unit vector
- (9) A matrix is symmetric.
- (10) A quadratic form/symmetric matrix is positive definite/negative definite/indefinite.