

Chapter 6 stuff

(§6.1)

Recall: • If $\vec{u} = \langle u_1, \dots, u_n \rangle$ & $\vec{v} = \langle v_1, \dots, v_n \rangle$, the dot prod.

is $\vec{u} \cdot \vec{v} = u_1 v_1 + \dots + u_n v_n$

↳ This is aka the inner product of \vec{u} & \vec{v} , which is written $\langle \vec{u}, \vec{v} \rangle$.

• Having an inner product allows us to ~~find~~ find lengths, & angles, distances,

• The length (or norm) of \vec{v} is $\|\vec{v}\| \stackrel{\text{def}}{=} \sqrt{\vec{v} \cdot \vec{v}}$

• The distance between \vec{u} & \vec{v} is $\text{dist}(\vec{u}, \vec{v}) \stackrel{\text{def}}{=} \|\vec{u} - \vec{v}\|$

• The angle between \vec{u} & \vec{v} is θ s.t. $\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$ } sometimes write $\angle(\vec{u}, \vec{v}) = \cos^{-1} \left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \right)$

• Ex! let $\vec{u} = \langle 1, 0, 1 \rangle$, $\vec{v} = \langle 2, 2, 1 \rangle$. Find:

• $\vec{u} \cdot \vec{v} = 2 + 0 + 1 = 3$

• $\|\vec{u}\| = \sqrt{1^2 + 0^2 + 1^2} = \sqrt{2}$; $\|\vec{v}\| = \sqrt{2^2 + 2^2 + 1^2} = \sqrt{9} = 3$

• $\text{dist}(\vec{u}, \vec{v}) = \|\vec{u} - \vec{v}\| = \|\langle -1, -2, 0 \rangle\| = \sqrt{(-1)^2 + (-2)^2 + 0^2} = \sqrt{5}$

Note: $\|\vec{v} - \vec{u}\| = \|\langle 1, 2, 0 \rangle\| = \sqrt{(1)^2 + (2)^2 + 0^2} = \sqrt{5}$, so order doesn't matter

• $\angle(\vec{u}, \vec{v}) = \cos^{-1} \left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \right) = \cos^{-1} \left(\frac{3}{3\sqrt{2}} \right) = \cos^{-1} \left(\frac{1}{\sqrt{2}} \right) = \frac{\pi}{4}$

- In linear algebra, we really care about orthogonality (i.e. being perpendicular)

Fact: \vec{u} is orthogonal to \vec{v} (written: $\vec{u} \perp \vec{v}$) iff $\vec{u} \cdot \vec{v} = 0$.

↳ This implies the pythagorean thm: $\vec{u} \perp \vec{v} \Leftrightarrow \|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$

Def: The orthogonal complement of a subspace W of \mathbb{R}^n is the subspace W^\perp of \mathbb{R}^n consisting of all vectors which are orthogonal to W :

$$W^\perp = \left\{ \vec{v} \in \mathbb{R}^n : \langle \vec{v}, \vec{w} \rangle = 0 \text{ for } \underline{\text{all}} \vec{w} \in W \right\}.$$

Ex: let $\vec{u} = \langle 1, 0, 0 \rangle$, $\vec{v} = \langle 0, 2, 0 \rangle \in \mathbb{R}^3$, & let $W = \text{span}\{\vec{u}, \vec{v}\}$.

Note: $W = xy$ -plane in \mathbb{R}^3 . & \vec{u}, \vec{v} are a basis for W . To find W^\perp , look for a vector that's \perp to every vector in the basis for W . Here, $\langle 0, 0, \square \rangle$ is \perp to \vec{u} & \vec{v} for all \square :

$$\langle 1, 0, 0 \rangle \cdot \langle 0, 0, \square \rangle = 0 \quad \underline{\text{and}} \quad \langle 0, 2, 0 \rangle \cdot \langle 0, 0, \square \rangle = 0.$$

So, $W^\perp = \text{span}\{\langle 0, 0, 1 \rangle\}$.

Observe: • The only vector in W and W^\perp is $\vec{0}$.

• If W is a subspace of \mathbb{R}^n , then $\dim(W) + \dim(W^\perp) = n$.

• Now, we want to put this together w/ stuff from Ch 4!

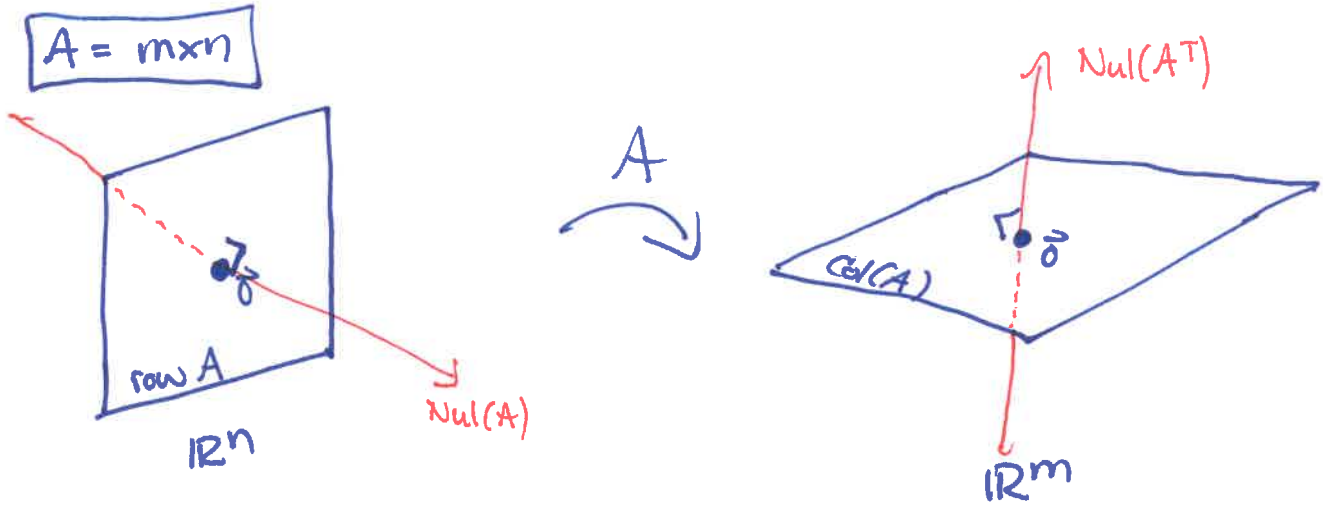
Theorem: For any matrix A ,

Logic: use $\textcircled{1}$ w/ A^T : $(\text{Row}(A^T))^\perp = \text{Nul}(A^T)$
 $\Leftrightarrow (\text{Col}(A))^\perp = \text{Nul}(A^T)$

$\textcircled{1} (\text{Row } A)^\perp = \text{Nul}(A) \quad \& \quad (\text{Col } A)^\perp = \text{Nul}(A^T)$

Logic: $\vec{x} \in \text{Nul}(A) \Leftrightarrow A\vec{x} = \vec{0}$, but components of $A\vec{x}$ are (rows of A) $\cdot \vec{x}$...

Here's one pic; for the other, see our webpage!



Ex: (From old class notes) [Found $\text{Nul}(A) = \text{span} \{ \langle -3, -2, 1, 1, 0 \rangle, \langle -9/4, -4, 7/4, 0, 1 \rangle \}$]

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & -1 & -2 & 6 & 4 \\ -1 & 1 & 1 & -2 & 0 \\ 2 & 4 & 6 & 8 & 10 \end{pmatrix} \xrightarrow{\text{r.e.}} \begin{pmatrix} 1 & 0 & 0 & 3 & 9/4 \\ 0 & 1 & 0 & 2 & 4 \\ 0 & 0 & 1 & -1 & -7/4 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

• $\text{row}(A) = \text{span} \{ \underbrace{\langle 1, 0, 0, 3, 9/4 \rangle}_{S_1}, \underbrace{\langle 0, 1, 0, 2, 4 \rangle}_{S_2}, \underbrace{\langle 0, 0, 1, -1, -7/4 \rangle}_{S_3} \}$
 is a 3D subspace of \mathbb{R}^5 .

$\hookrightarrow (\text{row}(A))^\perp$ is a 2D subspace w/ basis (e.g.)

$$\{ \underbrace{\langle -3, -2, 1, 1, 0 \rangle}_u, \underbrace{\langle -9/4, -4, 7/4, 0, 1 \rangle}_v \}$$

Check: $u \cdot S_1 = 0, u \cdot S_2 = 0, u \cdot S_3 = 0$
 $v \cdot S_1 = 0, v \cdot S_2 = 0, v \cdot S_3 = 0$

Ex (cont'd)

- using $\text{RREF}(A)$,

$$\text{Basis for } \text{col}(A) = \left\{ \overbrace{\langle 1, 2, -1, 2 \rangle}^{a_1}, \overbrace{\langle 2, -1, 1, 4 \rangle}^{a_2}, \overbrace{\langle 3, -2, 1, 6 \rangle}^{a_3} \right\}$$

3D subspace of \mathbb{R}^4 . $\Rightarrow \text{nul}(A^T)$ has $\dim = 1$

↳ • Can find $\text{nul}(A^T)$ by taking A^T & solving $(A^T)\vec{x} = \vec{0}$ (easy but long), or ...

• ... by finding one vector $\langle v_1, v_2, v_3, v_4 \rangle$ orthogonal to $a_1, a_2,$ and a_3 (short in theory but hard...)

Long way: $A^T = \begin{pmatrix} 1 & 2 & -1 & 2 \\ 2 & -1 & 1 & 4 \\ 3 & -2 & 1 & 6 \\ 4 & 6 & -2 & 8 \\ 5 & 4 & 0 & 10 \end{pmatrix} \xrightarrow{\text{RREF}} \begin{pmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \text{ so}$

$$A^T \vec{x} = \vec{0} \Rightarrow \vec{x} = x_4 \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\Rightarrow \text{Nul}(A^T) = \text{span} \left\{ \langle -2, 0, 0, 1 \rangle \right\}.$$

check: $\langle -2, 0, 0, 1 \rangle \cdot a_1 = 0$
 $\langle -2, 0, 0, 1 \rangle \cdot a_2 = 0$
 $\langle -2, 0, 0, 1 \rangle \cdot a_3 = 0$