

§ 1.7 - Linear Independence

Def. The vector $\vec{0}$ is called the trivial solution to

the equation

$$x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{0}$$

$$\left(\text{or } \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_p \end{bmatrix} \vec{x} = \vec{0} \right. \\ \left. A \vec{x} = \vec{0} \dots \right).$$

Note: The vector eq.

$$x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{0}$$

always has a solution:

In particular, if

$$x_1 = 0, \dots, x_p = 0,$$

the eq. is true!

Question: when is $\vec{0}$ the only solution?

"Ans": Sometimes but not always.

Ex: ① $\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\Leftrightarrow \begin{pmatrix} 2 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \boxed{x_2 = 0}$$

$$2x_1 + x_2 = 0 \Rightarrow 2x_1 = 0 \\ \Rightarrow \boxed{x_1 = 0.}$$

only trivial sol'n

② $\begin{pmatrix} 2 & 1 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\Leftrightarrow \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow 2x_1 + x_2 = 0$$

$$\Leftrightarrow \boxed{\begin{matrix} x_1 = \frac{x_2}{2} \\ x_2 = \text{free} \end{matrix}}$$

∞ -many sol'n
(incl. trivial one!)

Def: The set of vectors $\vec{v}_1, \dots, \vec{v}_p$ is linearly independent if $[\vec{v}_1 | \dots | \vec{v}_p] \vec{x} = \vec{0}$ has only the trivial solution. If not, linearly dependent.

↳ Having nontrivial solution \Leftrightarrow There existing x_1, \dots, x_p not all zero such that $x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{0}$

Q: If nontrivial solution, how many solutions? \Leftrightarrow ~~Some~~ ≥ 1 of the vectors $\vec{v}_1, \dots, \vec{v}_p$ is a linear combo of the other vectors.

Ans: ∞ -many! $\Leftrightarrow A\vec{x} = \vec{0}$ has free vars.

Ex
HW 1
#11(i)

Do $\vec{v}_1 = \begin{pmatrix} 1 \\ 6 \\ 4 \end{pmatrix}$ $\vec{v}_2 = \begin{pmatrix} 0 \\ 3 \\ 2 \end{pmatrix}$ $\vec{v}_3 = \begin{pmatrix} -2 \\ 6 \\ -3 \end{pmatrix}$ form a linearly independent set?

Ans: Try to solve $\vec{0} = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 3 & 6 \\ 4 & 2 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$ to get free vars!

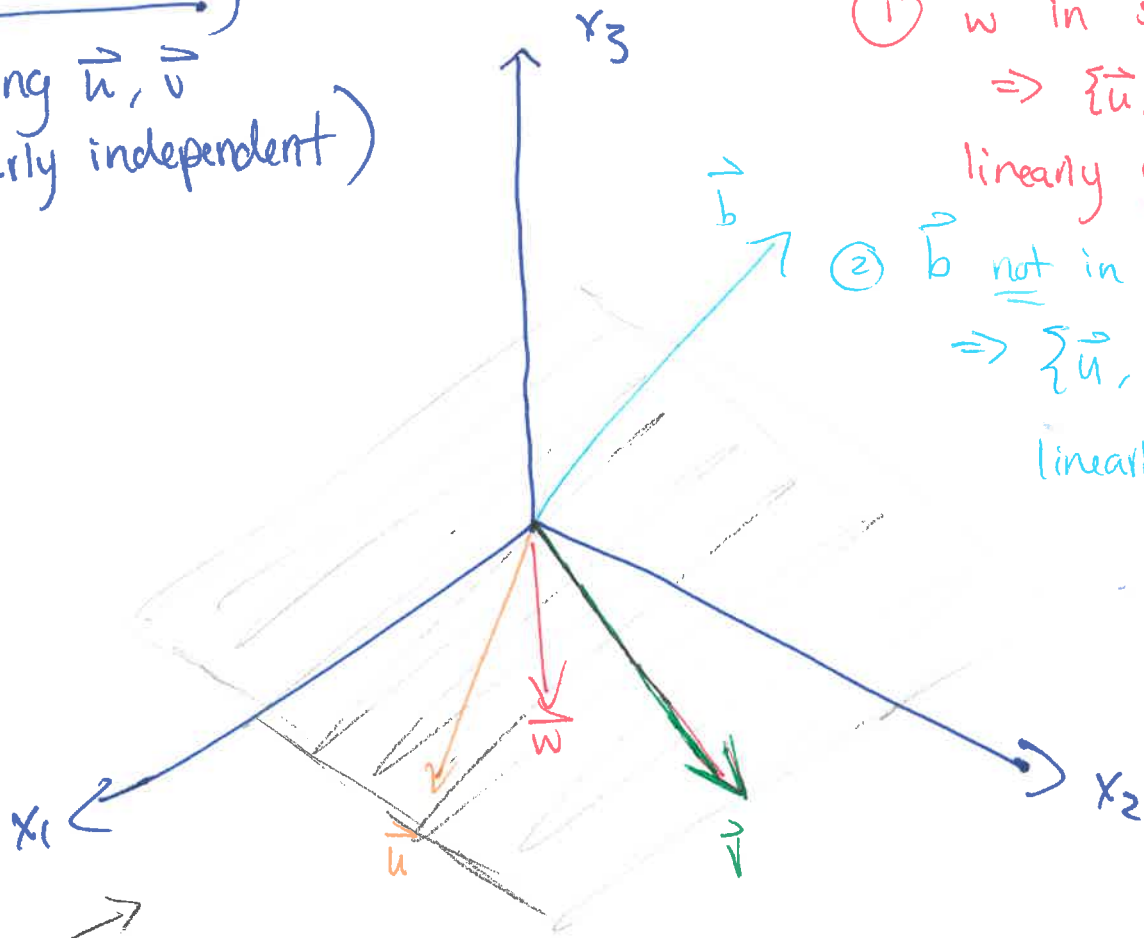
$$\begin{array}{l} \xrightarrow{R_2 = R_2 - 4R_1} \begin{pmatrix} 1 & 0 & -2 \\ 0 & 3 & 6 \\ 0 & 2 & 5 \end{pmatrix} \xrightarrow{R_3 = R_3 - \frac{2}{3}R_2} \begin{pmatrix} 1 & 0 & -2 \\ 0 & 3 & 6 \\ 0 & 0 & 1 \end{pmatrix} \\ \begin{array}{l} \uparrow -3 - 4(-2) \\ \uparrow 5 - \frac{2}{3}(6) \end{array} \end{array}$$

$$\vec{0} = A\vec{x} \Leftrightarrow \vec{0} = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 3 & 6 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \Leftrightarrow \begin{array}{l} \textcircled{1} x_3 = 0 \\ \textcircled{2} 3x_2 + 6(0) = 0 \Rightarrow x_2 = 0 \\ \textcircled{3} x_1 - 2(0) = 0 \Rightarrow x_1 = 0. \end{array}$$

So: only trivial solution to $A\vec{x} = \vec{0} \Rightarrow$ linearly independent.

Geometrically

(assuming \vec{u}, \vec{v} linearly independent)



infinite plane
(whole x_1, x_2 -plane)
is $\text{span}\{\vec{u}, \vec{v}\}$

① \vec{w} in $\text{span}\{\vec{u}, \vec{v}\}$
 $\Rightarrow \{\vec{u}, \vec{v}, \vec{w}\}$
linearly dependent.

② \vec{b} not in $\text{span}\{\vec{u}, \vec{v}\}$
 $\Rightarrow \{\vec{u}, \vec{v}, \vec{b}\}$
linearly independent.

§ 1.7 (Cont'd)

Recall: • $\{\vec{v}_1, \dots, \vec{v}_p\}$ is Linearly Independent (L.I.) if the vector equation $x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{0}$ has only the trivial solution and is Linearly dependent (L.D.) otherwise.

↳ $A\vec{x} = \vec{0}$ is called "homogeneous equation" b/c of the " $= \vec{0}$ ".

From last time: $\{\vec{v}_1, \dots, \vec{v}_p\}$ L.I. \Leftrightarrow the system corresponding to augmented matrix $[\vec{v}_1 | \dots | \vec{v}_p | \vec{0}]$ has no free variables.

Ex: If $\vec{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}$, $\vec{v}_3 = \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix}$, is $\{\vec{v}_1, \dots, \vec{v}_3\}$ L.I.?

$$\begin{pmatrix} 1 & 4 & 7 & 0 \\ 2 & 5 & 8 & 0 \\ 3 & 6 & 9 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 4 & 7 & 0 \\ 0 & -3 & -6 & 0 \\ 0 & -6 & -12 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 4 & 7 & 0 \\ 0 & -3 & -6 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Not L.I.

HOW TO PICTURE IT GEOMETRICALLY

The vectors $\{\vec{v}_1, \dots, \vec{v}_p\}$ in \mathbb{R}^m is L.I. if

$$\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$$

is a p -dimensional region in \mathbb{R}^m & L.D. otherwise!

Facts from this

① $\{\vec{v}\}$ is L.I. if $\text{span}\{\vec{v}\}$ is 1-dim space

$\vec{v} \neq \vec{0}$. $\left(\begin{array}{l} \text{if } \vec{v} = \vec{0}, \text{ span} = \vec{0} = \\ \text{pt (0-dim); otherwise,} \\ \text{span} = \text{line} = 1\text{-dim} \end{array} \right)$

② $\{\vec{u}, \vec{v}\}$ is L.I. if $\text{span}\{\vec{u}, \vec{v}\}$ is 2-dim space (plane)

\vec{u} & \vec{v} not collinear

\vec{u} & \vec{v} not scalar multiples of one another.

Ex: (i) $\left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 1.5 \\ 0 \end{pmatrix} \right\} \rightarrow \text{L.D.}$

$\left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 4 \\ 0 \end{pmatrix} \right\} \rightarrow \text{L.I.}$

(ii) let $\vec{u} = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$, $\vec{v} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$.

Describe $\text{span}\{\vec{u}, \vec{v}\}$ &

explain why $\vec{w} \notin \text{span}\{\vec{u}, \vec{v}\}$

iff $\{\vec{u}, \vec{v}, \vec{w}\}$ L.D.

③ If a set contains more vectors than there are entries in each vector, then L.D., i.e. $\{\vec{v}_1, \dots, \vec{v}_p\}$ L.D. in \mathbb{R}^n if $p > n$.

Ex: $\left\{ \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}, \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \right\}$ L.D. b/c L.I. $\Leftrightarrow \text{span}\{\vec{u}, \vec{v}, \vec{w}\}$ is a 3-dim subspace of \mathbb{R}^2 , but no such subspaces exist.

(cont'd)

④ $\underbrace{\{\vec{v}_1, \dots, \vec{v}_p\}}_{=S}$ L.D. if any vector in S is a linear combo of the others.

Why? If this is true, then the system corresponding to $[\vec{v}_1 | \dots | \vec{v}_p] \begin{pmatrix} x_1 \\ \vdots \\ x_p \end{pmatrix} = \vec{0}$ will have a free var!

Ex: let $v_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$, $v_2 = \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix}$, and $v_3 = v_1 + 2v_2$. Then

$$\begin{aligned} [\vec{v}_1 | \dots | \vec{v}_3 | \vec{0}] &= \begin{pmatrix} 1 & 2 & 5 & 0 \\ 2 & 0 & 2 & 0 \\ 3 & -1 & 1 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 5 & 0 \\ 0 & -4 & -8 & 0 \\ 0 & -5 & -14 & 0 \end{pmatrix} \\ &\sim \begin{pmatrix} 1 & 2 & 5 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & \cancel{1} & \cancel{2} & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 5 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & \cancel{1} & 0 \end{pmatrix} \leftarrow \text{Free var!} \end{aligned}$$

⑤ If $\{\vec{v}_1, \dots, \vec{v}_p\}$ contains the zero vector, then L.D!

Why? $\vec{0} = 0 \cdot \vec{v}_1 + \dots + 0 \cdot \vec{v}_{p-1}$, regardless of what $\vec{v}_1, \dots, \vec{v}_{p-1}$ is!

Ex: Do a HW problem!