

1. (a) • Is linear (will give details for some later parts)

• domain =  $\mathbb{R}^2$

codomain =  $\mathbb{R}^2$

range =  $\mathbb{R}^2 \leftarrow \text{RHS} = \begin{pmatrix} y \\ x \end{pmatrix} = y \begin{pmatrix} 1 \\ 0 \end{pmatrix} + x \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$= y \vec{v}_1 + x \vec{v}_2$  where  $\vec{v}_1, \vec{v}_2$  L.I.  
 $\approx \mathbb{R}^2$

•  $T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ ;  $T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

•  $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

•  $T$  is injective (A has L.I. columns)

•  $T$  is surjective (codom(T) = range(T)).

For linear  
LHS =  $T(c\vec{u} + d\vec{v})$   
RHS =  $cT(\vec{u}) + dT(\vec{v})$

(b) • is linear

$\hookrightarrow$  let  $\vec{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$  &  $\vec{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$ . Then LHS =  $T(c\vec{u} + d\vec{v}) =$

$T \begin{pmatrix} cu_1 + dv_1 \\ cu_2 + dv_2 \end{pmatrix} = \begin{pmatrix} cu_1 + dv_1 \\ cu_1 + dv_1 \end{pmatrix}$  & RHS =  $cT \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} + dT \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} =$

$c \begin{pmatrix} u_1 \\ u_1 \end{pmatrix} + d \begin{pmatrix} v_1 \\ v_1 \end{pmatrix} = \begin{pmatrix} cu_1 + dv_1 \\ cu_1 + dv_1 \end{pmatrix}$ . Hence, LHS = RHS.

• domain =  $\mathbb{R}^2$ ; codomain =  $\mathbb{R}^2$ ; Range =  $\mathbb{R}$

•  $T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ ;  $T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

•  $A = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$

• Not injective (cols of A are L.D.)

• Not surjective (codom(T)  $\neq$  range(T))

$\begin{pmatrix} x \\ x \end{pmatrix} = x \begin{pmatrix} 1 \\ 1 \end{pmatrix} = x \vec{v}$ , where  $\vec{v}$  L.I.  
so range  $\approx \mathbb{R}$ .

(c) • is linear

$$\hookrightarrow \text{LHS} = T \begin{pmatrix} cu_1 + dv_1 \\ cu_2 + dv_2 \end{pmatrix} = \begin{pmatrix} (cu_1 + dv_1) + (cu_2 + dv_2) \\ cu_1 + dv_1 \end{pmatrix}$$

$$\begin{aligned} \text{RHS} &= cT \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} + dT \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} cu_1 + cu_2 \\ cu_1 \end{pmatrix} + \begin{pmatrix} dv_1 + dv_2 \\ dv_1 \end{pmatrix} \\ &= \begin{pmatrix} cu_1 + dv_1 + cu_2 + dv_2 \\ cu_1 + dv_1 \end{pmatrix} = \text{LHS}. \end{aligned}$$

• Domain =  $\mathbb{R}^2$ ; codom =  $\mathbb{R}^2$ ; range =  $\mathbb{R}^2$

•  $T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ ;  $T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$\hookrightarrow \begin{pmatrix} x+y \\ x \end{pmatrix} = x \begin{pmatrix} 1 \\ 1 \end{pmatrix} + y \begin{pmatrix} 1 \\ 0 \end{pmatrix} = x\vec{v}_1 + y\vec{v}_2$$

where  $\vec{v}_1, \vec{v}_2$  l.i. So range =  $\mathbb{R}^2$ .

•  $A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$

• is injective (A has l.i. cols)

• is surjective (range(T) = codom(T))

(d) • is linear

• Domain =  $\mathbb{R}^2$ ; codom =  $\mathbb{R}^2$ ; range =  $\mathbb{R}$

•  $T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ ;  $T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\hookrightarrow \begin{pmatrix} 0 \\ y \end{pmatrix} = y \begin{pmatrix} 0 \\ 1 \end{pmatrix} = y\vec{v} \Rightarrow \text{Range} = \mathbb{R}$$

•  $A = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

• Not injective (A has l.d. cols)

• Not surjective (range  $\neq$  codom; also,  $\begin{pmatrix} \# \\ y \end{pmatrix}$  not hit if  $\# \neq 0$ )

(e) • is linear

• dom =  $\mathbb{R}^3$ ; codom =  $\mathbb{R}^2$ ; range =  $\mathbb{R}^2$

$$\tau \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}; \tau \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix};$$

$$\tau \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

• Not injective (A has L.D. cols)

• is surjective (codom = range)

$$\begin{pmatrix} x \\ y \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \end{pmatrix} = x \vec{v}_1 + y \vec{v}_2 \quad \text{w/ } \vec{v}_1, \vec{v}_2 \text{ L.I.} \\ \Rightarrow \text{range} = \mathbb{R}^2$$

Note: This DOESN'T violate the invertible matrix theorem; that only holds for square matrices!

(f) • is linear

• dom =  $\mathbb{R}^3$ ; codom =  $\mathbb{R}^3$ ; range =  $\mathbb{R}^2$

$$\tau \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}; \tau \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix};$$

$$\tau \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

• Not injective (A has L.D. cols)

• Not surjective (codom  $\neq$  range)

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = x \vec{v}_1 + y \vec{v}_2 \quad \text{w/ } \vec{v}_1, \vec{v}_2 \text{ L.I.} \\ \Rightarrow \text{range} \approx \mathbb{R}^2$$

Also, not injective + square  $\Rightarrow$  not surjective by inverse matrix thm!

(g) • linear

• dom =  $\mathbb{R}^3$ ; cod =  $\mathbb{R}^4$ ; range =  $\mathbb{R}^3$

$$\tau \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}; \tau \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}; \tau \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

• injective (A has L.I. cols)

• not surjective (range  $\neq$  codom)

$$\begin{pmatrix} x \\ y \\ z \\ 0 \end{pmatrix} = x \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + z \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \\ = x \vec{v}_1 + y \vec{v}_2 + z \vec{v}_3 \quad \text{w/ } \vec{v}_1, \vec{v}_2, \vec{v}_3 \text{ L.I.} \\ \Rightarrow \text{range} \approx \mathbb{R}^3$$

(h) • is linear

- $\text{dom} = \mathbb{R}^4$ ;  $\text{codom} = \mathbb{R}^4$ ;  $\text{range} = \mathbb{R}^4$  ←  $\begin{pmatrix} 3 \\ x \\ y \\ z \end{pmatrix} = w \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + y \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$   
 $= w\vec{v}_1 + x\vec{v}_2 + y\vec{v}_3 + z\vec{v}_4$  w/ all vectors L.I.  $\Rightarrow \text{range} \approx \mathbb{R}^4$
- $T\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ ;  $T\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$ ;
- $T\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$ ;  $T\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$
- $A = I_4 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$
- injective (A has L.I. cols)
- surjective (range = codom)

=

(i) • is linear

- $\text{dom} = \mathbb{R}^4$ ;  $\text{codom} = \mathbb{R}$ ;  $\text{range} = \mathbb{R}$

$$T\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = 1; T\begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = 1;$$

$$T\begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = 1; T\begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = 1.$$

$$A = \langle 1, 1, 1, 1 \rangle$$

• Not injective

(A has L.I. cols)

• surjective (codom = range).

$$\uparrow (w+x+y+z) = w(1) + x(1) + y(1) + z(1)$$

$$(*) \cong w\vec{v}_1 + x\vec{v}_2 + y\vec{v}_3 + z\vec{v}_4 \text{ where}$$

$\vec{v}_2, \vec{v}_3, \vec{v}_4$  dependent on  $\vec{v}_1 \Rightarrow \text{range} = c \cdot \vec{v}_1$

for some constant  $c \Rightarrow \text{range} \approx \mathbb{R}$ .

(one L.I. vector in  $(*) \Rightarrow \text{range} = \mathbb{R}^1 = \mathbb{R}$ )

$$3. S: \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} x_2 \\ x_1 \end{pmatrix} \Rightarrow A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

(a)

$$T: \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \mapsto \begin{pmatrix} y_2 \\ y_1 \end{pmatrix} \Rightarrow B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\Rightarrow T \circ S \text{ has matrix } BA = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$(b) S: \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} \Rightarrow A = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$T: \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \mapsto \begin{pmatrix} y_1 \\ y_2 \\ y_1 + 2y_2 \end{pmatrix} \Rightarrow B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 2 \end{pmatrix}$$

$$\Rightarrow T \circ S \text{ has matrix } BA = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 2 \end{pmatrix}$$

$$(c) S: \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto \begin{pmatrix} x_1 - x_2 \\ x_2 - x_3 \\ x_1 + x_2 + x_3 \\ x_1 \end{pmatrix} \Rightarrow A = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$T: \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} \mapsto \begin{pmatrix} y_1 \\ y_2 - y_3 - y_4 \end{pmatrix} \Rightarrow B = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 \end{pmatrix}$$

$$\Rightarrow T \circ S \text{ has matrix } BA = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 1 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & -1 & 0 \\ -2 & 0 & -2 \end{pmatrix}$$

4. (a) •  $A^3$  DNE

- $A^T = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$
- $\det(A)$  DNE
- $A^{-1}$  DNE

(b) •  $A^3$  DNE

- $A^T = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}$
- $\det(A)$  DNE
- $A^{-1}$  DNE

(c) •  $A^3 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

- $A^T = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
- $\det(A) = 1$
- $A^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

(d) •  $A^3 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

- $A^T = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$
- $\det(A) = 0$
- $A^{-1}$  DNE

(e) •  $A^3 = \begin{pmatrix} 37 & 54 \\ 81 & 118 \end{pmatrix}$

- $A^T = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$
- $\det(A) = 1(4) - 3(2) = -2$
- $A^{-1} = \begin{pmatrix} -2 & 1 \\ 3/2 & -1/2 \end{pmatrix}$

(f) •  $A^3 = \begin{pmatrix} 13 & 8 \\ 8 & 5 \end{pmatrix}$

- $A^T = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$
- $\det(A) = 1$
- $A^{-1} = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$

(g) •  $A^3 = \begin{pmatrix} 1 & 42 & 239 \\ 0 & 64 & 380 \\ 0 & 0 & 216 \end{pmatrix}$

- $A^T = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 4 & 0 \\ 3 & 5 & 6 \end{pmatrix}$
- $\det(A) = 24$
- $A^{-1} = \begin{pmatrix} 1 & -1/2 & -1/12 \\ 0 & 1/4 & -5/24 \\ 0 & 0 & 1/6 \end{pmatrix}$

(h) •  $A^3 = \begin{pmatrix} 510 & 624 & 834 \\ 1146 & 1401 & 1872 \\ 2014 & 2462 & 3290 \end{pmatrix}$

- $A^T = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 11 \end{pmatrix}$
- $\det(A) = -6$
- $A^{-1} = \begin{pmatrix} -7/6 & -1/3 & 1/2 \\ 1/3 & 5/3 & -1 \\ 1/2 & -1 & 1/2 \end{pmatrix}$

(i) •  $A^3 = \begin{pmatrix} -6 & -14 & -3 & 25 \\ 12 & 85 & 70 & -63 \\ -39 & -5 & 23 & 80 \\ 59 & 52 & 5 & -143 \end{pmatrix}$

•  $A^T = \begin{pmatrix} 1 & 1 & -2 & 3 \\ -1 & 4 & 0 & 2 \\ 1 & 4 & 1 & 1 \\ 2 & -2 & 3 & -5 \end{pmatrix}$

•  $\det(A) = -12$

•  $A^{-1} = \begin{pmatrix} 1/3 & 5/6 & -13/6 & -3/2 \\ -1/6 & 19/12 & -41/12 & -1/4 \\ 1/6 & -13/12 & 35/12 & 1/4 \\ 1/6 & 11/12 & -25/12 & -7/4 \end{pmatrix}$

Note:  $\det(A) = 0 \Rightarrow A^{-1}$  DNE.

5. Let  $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$ . Write **true** or **false** for each of the following statements about  $A$ .

**Hint:** You may not need to work super-hard for most of these!

- (a)  $Ax = \mathbf{0}$  has non-trivial solutions. **True**
- (b) The RREF of  $A$  is equal to the  $3 \times 3$  identity matrix  $I_3$ . **False**
- (c) The columns of  $A$  form a linearly dependent set. **True**
- (d) The transformation  $x \mapsto Ax$  is one-to-one. **False**
- (e) The transformation  $x \mapsto Ax$  is onto. **False**
- (f) The columns of  $A$  span  $\mathbb{R}^3$ . **False**
- (g) The range of the transformation  $x \mapsto Ax$  equals its codomain. **False**
- (h) The matrix  $A^{-1}$  exists. **False**
- (i)  $\det(A) = 7$ . **False**
- (j) There exists some  $\mathbf{b} \in \mathbb{R}^3$  for which  $Ax = \mathbf{b}$  doesn't have a solution. **True**
- (k)  $A^T$  is invertible. **False**

↑  
All follows from invertible matrix thm!