

1. (a) •  $A^4$  DNE ( $A$  not square)

$$\bullet A^T = \begin{pmatrix} 1 & 5 \\ 2 & 6 \\ 3 & 7 \\ 4 & 8 \end{pmatrix}$$

•  $A^{-1}$  DNE ( $A$  not square)

(b) •  $A^4$  DNE (not square)

$$\bullet A^T = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{pmatrix}$$

•  $A^{-1}$  DNE (not square)

(c) •  $A^4 = \begin{pmatrix} 7560 & 9288 & 11016 \\ 17118 & 21033 & 24948 \\ 26676 & 32778 & 38880 \end{pmatrix}$

$$\bullet A^T = \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$$

•  $A^{-1}$  DNE ( $\det(A) = 0$ )

(d) •  $A^4 = \begin{pmatrix} 7497 & 9144 & 9036 \\ 17040 & 20793 & 20568 \\ 24928 & 30436 & 30145 \end{pmatrix}$

$$\bullet A^T = \begin{pmatrix} 1 & 4 & 8 \\ 2 & 5 & 9 \\ 3 & 6 & 7 \end{pmatrix}$$

$$\bullet A^{-1} = \begin{pmatrix} -19/9 & 13/9 & -1/3 \\ 20/9 & -17/9 & 2/3 \\ -4/9 & 7/9 & -1/3 \end{pmatrix}$$

2. (a) True. If  $\vec{u} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{pmatrix}$  &  $\vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix}$ , then

• LHS  $\stackrel{\text{def}}{=} \tau(\vec{c}\vec{u} + d\vec{v})$

$$= \tau \begin{pmatrix} cu_1 + dv_1 \\ cu_2 + dv_2 \\ cu_3 + dv_3 \\ cu_4 + dv_4 \end{pmatrix} = \begin{pmatrix} (cu_1 + dv_1) - (cu_3 + dv_3) \\ (cu_4 + dv_4) - (cu_2 + dv_2) \\ -(cu_1 + dv_1) - (cu_2 + dv_2) + (cu_3 + dv_3) \\ -(cu_4 + dv_4) \end{pmatrix}$$

• RHS  $\stackrel{\text{def}}{=} c\tau(\vec{u}) + d\tau(\vec{v})$

$$= c \begin{pmatrix} u_1 - u_3 \\ u_4 - u_2 \\ -u_1 - u_2 + u_3 - u_4 \end{pmatrix} + d \begin{pmatrix} v_1 - v_3 \\ v_4 - v_2 \\ -v_1 - v_2 + v_3 - v_4 \end{pmatrix}$$

$$= \begin{pmatrix} cu_1 - cu_3 + dv_1 - dv_3 \\ cu_4 - cu_2 + dv_4 - dv_2 \\ -cu_1 - cu_2 + cu_3 - cu_4 + dv_1 - dv_2 + dv_3 - dv_4 \end{pmatrix}$$

= LHS. [simplify LHS further if needed]

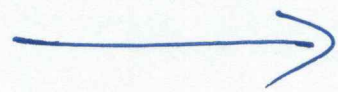
Hence,  $\tau$  linear!

(b)  $\tau \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$  •  $\tau \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ -1 \end{pmatrix}$  •  $\tau \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$  •  $\tau \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$

(c)  $A = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & -1 & 0 & 1 \\ -1 & -1 & 1 & -1 \end{pmatrix}$

(d)  $\text{dom}(A) = \mathbb{R}^4$

(e)  $\text{codom}(A) = \mathbb{R}^3$





2 (cont'd)

$$(f) \text{ Range}(T) = \mathbb{R}^3$$

↳ How?

(i) write parametric vector form of the right side of  $T$ :

$$\begin{pmatrix} x_1 - x_3 \\ x_4 - x_2 \\ -x_1 - x_2 + x_3 - x_4 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ -1 \\ -1 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

(ii) [optional] rewrite the vectors as  $\vec{v}_1, \dots$

$$\leadsto x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3 + x_4 \vec{v}_4$$

(iii) "Erase" any vector which is linearly dependent on the others:

↳ Notice:  $\vec{v}_3 = -\vec{v}_1$  so erase  $\vec{v}_3$ ; none of the others need to be erased.

(iv) Rewrite:

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_4 \vec{v}_4$$

(v) your answer is  $\mathbb{R}^k$  where  $k = \#$  of vectors not thrown away!

$$\leadsto x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_4 \vec{v}_4 \leadsto \underline{\underline{\mathbb{R}^3}}$$

• Note: Range =  $\mathbb{R}^3$  = Codomain!



2 (cont'd)

(h) Not injective!  $\leadsto \text{col } 3 = -\text{col } 1$ , so  $A$  doesn't have L.I. columns!

(i) is surjective!  $\leadsto \text{range}(T) = \mathbb{R}^3 = \text{codomain}$   
so  $T$  is onto.

3. (a)  $A = \begin{pmatrix} 1 & -1 & 0 & -1 \\ 1 & 1 & -1 & 0 \end{pmatrix}$

(b)  $B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \\ -3 & 2 \\ 1 & 0 \end{pmatrix}$

(c)  $BA = \begin{pmatrix} 1 & 1 & -1 & 0 \\ -1 & 1 & 0 & 1 \\ -1 & 5 & -2 & 3 \\ 1 & -1 & 0 & -1 \end{pmatrix}$

(d)  $\det(BA) = 0$

(e)  $AB = \begin{pmatrix} 0 & 1 \\ 2 & -1 \end{pmatrix}$

(f)  $\det(AB) = -2$

(g) } Both False b/c  $A^{-1}, B^{-1}$  DNE (neither is square)

(h) }



$$\begin{aligned}
 4. (a) \det(A) &= +1 \cdot \det \begin{pmatrix} 5 & 6 \\ 8 & 9 \end{pmatrix} \\
 &\quad - 4 \det \begin{pmatrix} 2 & 3 \\ 8 & 9 \end{pmatrix} \\
 &\quad + 0 \cdot \det \begin{pmatrix} 2 & 3 \\ 5 & 6 \end{pmatrix} \\
 &= (45 - 48) - 4(18 - 24) + 0 \\
 &= -3 - 4(-6) \\
 &= 21
 \end{aligned}$$

$$\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 0 & 8 & 9 \end{pmatrix}$$

$$(b) A^{-1} = \begin{pmatrix} -1/7 & 2/7 & -1/7 \\ -12/7 & 3/7 & 2/7 \\ 32/21 & -8/21 & -1/7 \end{pmatrix}$$

$$\begin{aligned}
 (c) \vec{x} &= A^{-1} \cdot \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \\
 &= \begin{pmatrix} -3/7 \\ -8/7 \\ 26/21 \end{pmatrix}
 \end{aligned}$$

5. Note! A is  $5 \times 5$  so invertible matrix thm applies!

(a)  $\vec{a}_5$  depends on  $\vec{a}_1, \dots, \vec{a}_4 \Rightarrow A$  has LD cols

$\Rightarrow T$  not one-to-one

$\Rightarrow A^{-1}$  not exist

$\Rightarrow \det(A) = 0$ .

(b)  $T$  reverses orientation  $\Rightarrow \det(A)$  negative

$\Rightarrow \det(A) \neq 0$

$A^{-1}$  exists  $\Rightarrow T$  one-to-one &  $T$  onto

$\Rightarrow A\vec{x} = \vec{b}$  has  $\leq 1$  sol'n &  $\geq 1$

$\Rightarrow A\vec{x} = \vec{b}$  has 1 sol'n

$\Rightarrow A^{-1}$  exists

$\Rightarrow A\vec{x} = \vec{b}$  has a unique solution

(c)  $\text{span}\{5 \text{ vecs}\} = \mathbb{R}^4 \Rightarrow$  one vec is L.D. on others

$\Rightarrow A$  has L.D. cols

$\Rightarrow T$  not 1-1

~~$\Rightarrow A^{-1}$  does not exist~~

$\Rightarrow A\vec{x} = \vec{0}$  has  $\infty$ -many sols.

(d)  $\begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \notin \text{range}(T) \Rightarrow \text{range}(T) \neq \text{cod}(T)$

$\Rightarrow T$  not surjective

$\Rightarrow A^{-1}$  not exist

From inverse/det handout,

$\det(A) = \det(A^T)$

$\Rightarrow \det(A) = 0$

$\Rightarrow \det(A^T) = 0$

$\Rightarrow \text{FALSE}$



## 5 (cont'd)

(e)  $(A \mid \vec{b})$  consistent  $\Rightarrow$  All  $\vec{b}$  in  $\mathbb{R}^5$  are in  
for all  $\vec{b} \in \mathbb{R}^5$  range(T)

$$\Rightarrow T \text{ onto}$$

$$\Rightarrow A^{-1} \text{ exists}$$

$$\Rightarrow A \text{ is r.e. to } I_5$$

$$\Rightarrow \det(\text{RREF}(A)) = \det(I_5)$$

$$\Rightarrow \det(\text{RREF}(A)) = 1.$$

(f)  $A\vec{x} = \vec{b}$  has  $> 1$   $\Rightarrow$  T not 1-1  
sol'n for some  $\vec{b}$

$A^{-1}$  not exist  $\Rightarrow$  A not r.e.

to  $I_5 \Rightarrow \text{RREF}(A) \neq I_5$

This means  $\det(\text{RREF}(A)) = 0$

$$\Rightarrow A^{-1} \text{ not exist}$$

$$\Rightarrow \det(A) = 0$$

$$\Rightarrow \det(\text{RREF}(A)) = 0$$

$$\Rightarrow \det(\text{RREF}(A^T)) = 0$$

}  $\det(\text{RREF}(A))$   
"  $\det(\text{RREF}(A^T))$   
by  
handout

(g) Cols of A l.i.  $\Rightarrow$  T 1-1

$$\Rightarrow A^{-1} \text{ exists}$$

$$\Rightarrow AA^{-1} = I_5$$

$$\Rightarrow \det(AA^{-1}) = \det(I_5)$$

$$\Rightarrow \det(A)\det(A^{-1}) = 1$$

$$\Rightarrow \det(A^{-1}) = 1/\det(A)$$

$$\Rightarrow \text{TRUE}$$

5 (cont'd)

$$(h) \text{ range}(T) = \mathbb{R}^5 \Rightarrow \text{range}(T) = \text{codom}(T)$$

$$\Rightarrow T \text{ onto}$$

$$\Rightarrow A^{-1} \text{ exists}$$

$$\Rightarrow T \text{ one-to-one}$$

$$\Rightarrow A \text{ has L.I. cols}$$

$$\Rightarrow \vec{a}_5 \notin \text{span}\{\vec{a}_1, \dots, \vec{a}_4\}$$

$$\Rightarrow \vec{a}_5 \neq c_1 \vec{a}_1 + c_2 \vec{a}_2 + c_3 \vec{a}_3 + c_4 \vec{a}_4$$

for any combo of  $c_1, \dots, c_4$

$$\Rightarrow \text{FALSE}$$

$$(i) \text{ Blc } \begin{pmatrix} \text{new} \\ \text{vol} \end{pmatrix} = |\det(A)| \cdot \begin{pmatrix} \text{old} \\ \text{vol} \end{pmatrix}, T \text{ mapping to} \\ \text{a region w/ } \underline{\text{strictly larger}} \text{ volume} \Rightarrow \det(A) \neq 0$$

$$\Rightarrow A^{-1} \text{ exists}$$

$$\Rightarrow T \text{ onto}$$

$$\Rightarrow \text{range}(T) = \text{codom}(T)$$

$$\Rightarrow \text{range}(T) = \mathbb{R}^5$$

$$\Rightarrow \text{span}\{\vec{a}_1, \dots, \vec{a}_5\} = \mathbb{R}^5.$$



6. Practice True/False questions by doing problems 1(a)–1(p) from the below except for parts (g)–(k):

1. Assume that the matrices mentioned in the statements below have appropriate sizes. Mark each statement True or False. Justify each answer.

a. If  $A$  and  $B$  are  $m \times n$ , then both  $AB^T$  and  $A^T B$  are defined. **True**

b. If  $AB = C$  and  $C$  has 2 columns, then  $A$  has 2 columns. **False**

c. Left-multiplying a matrix  $B$  by a diagonal matrix  $A$ , with nonzero entries on the diagonal, scales the rows of  $B$ . ~~False~~ **True**  
*AB, not BA* ↑ false w/ BA

d. If  $BC = BD$ , then  $C = D$ . **False**

e. If  $AC = 0$ , then either  $A = 0$  or  $C = 0$ . **False**

f. If  $A$  and  $B$  are  $n \times n$ , then  $(A + B)(A - B) = A^2 - B^2$ . **False**

~~g. An elementary  $n \times n$  matrix has either  $n$  or  $n + 1$  nonzero entries.~~

~~h. The transpose of an elementary matrix is an elementary matrix.~~ *skip.*

~~i. An elementary matrix must be square.~~

~~j. Every square matrix is a product of elementary matrices.~~

~~k. If  $A$  is a  $3 \times 3$  matrix with three pivot positions, there exist elementary matrices  $E_1, \dots, E_p$  such that  $E_p \cdots E_1 A = I$ .~~

l. If  $AB = I$ , then  $A$  is invertible. **False**

m. If  $A$  and  $B$  are square and invertible, then  $AB$  is invertible, and  $(AB)^{-1} = A^{-1}B^{-1}$ . **False**

n. If  $AB = BA$  and if  $A$  is invertible, then  $A^{-1}B = BA^{-1}$ . **True**

o. If  $A$  is invertible and if  $r \neq 0$ , then  $(rA)^{-1} = rA^{-1}$ . **False**

p. If  $A$  is a  $3 \times 3$  matrix and the equation  $Ax = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  has a unique solution, then  $A$  is invertible. **True.**



7. Practice True/False questions by doing problems 1(a)–1(p) from the below except for parts (f)–(h) and part (l):

1. Mark each statement True or False. Justify each answer. Assume that all matrices here are square.

a. If  $A$  is a  $2 \times 2$  matrix with a zero determinant, then one column of  $A$  is a multiple of the other. *True*

b. If two rows of a  $3 \times 3$  matrix  $A$  are the same, then  $\det A = 0$ . *True*

c. If  $A$  is a  $3 \times 3$  matrix, then  $\det 5A = 5 \det A$ . *False*

d. If  $A$  and  $B$  are  $n \times n$  matrices, with  $\det A = 2$  and  $\det B = 3$ , then  $\det(A + B) = 5$ . *False*

e. If  $A$  is  $n \times n$  and  $\det A = 2$ , then  $\det A^3 = 6$ . *False*

~~f. If  $B$  is produced by interchanging two rows of  $A$ , then  $\det B = \det A$ .~~

~~g. If  $B$  is produced by multiplying row 3 of  $A$  by 5, then  $\det B = 5 \cdot \det A$ .~~

~~h. If  $B$  is formed by adding to one row of  $A$  a linear combination of the other rows, then  $\det B = \det A$ .~~

i.  $\det A^T = -\det A$ . *False*

j.  $\det(-A) = -\det A$ . *False*

k.  $\det A^T A \geq 0$ . *True*

~~l. Any system of  $n$  linear equations in  $n$  variables can be solved by Cramer's rule.~~

m. If  $\mathbf{u}$  and  $\mathbf{v}$  are in  $\mathbb{R}^2$  and  $\det[\mathbf{u} \ \mathbf{v}] = 10$ , then the area of the triangle in the plane with vertices at  $\mathbf{0}$ ,  $\mathbf{u}$ , and  $\mathbf{v}$  is 10. *False*

n. If  $A^3 = 0$ , then  $\det A = 0$ . *True*

o. If  $A$  is invertible, then  $\det A^{-1} = \det A$ . *False*

p. If  $A$  is invertible, then  $(\det A)(\det A^{-1}) = 1$ . *True*