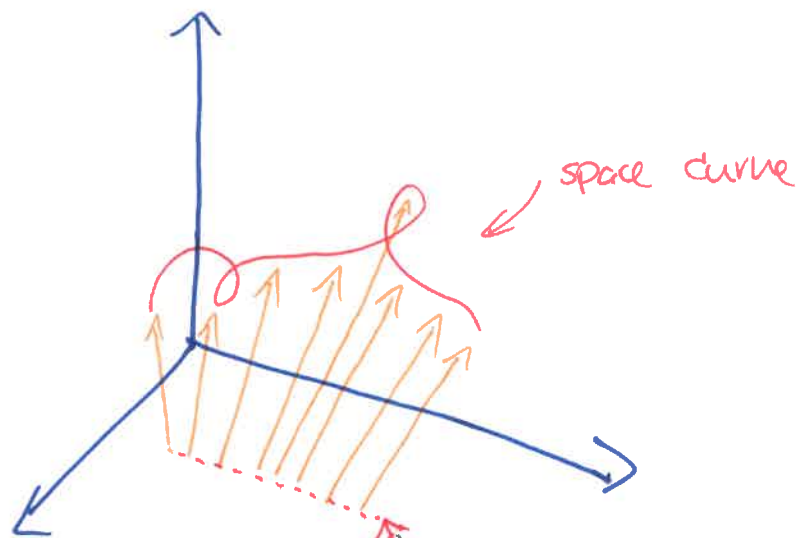


§16.6 - Parametric Surfaces

Recall! Space curves can be traced out by vector functions

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle.$$

↳ The idea is that a vector moves along a "t-axis" a (1D) & its tip traces out a curve.

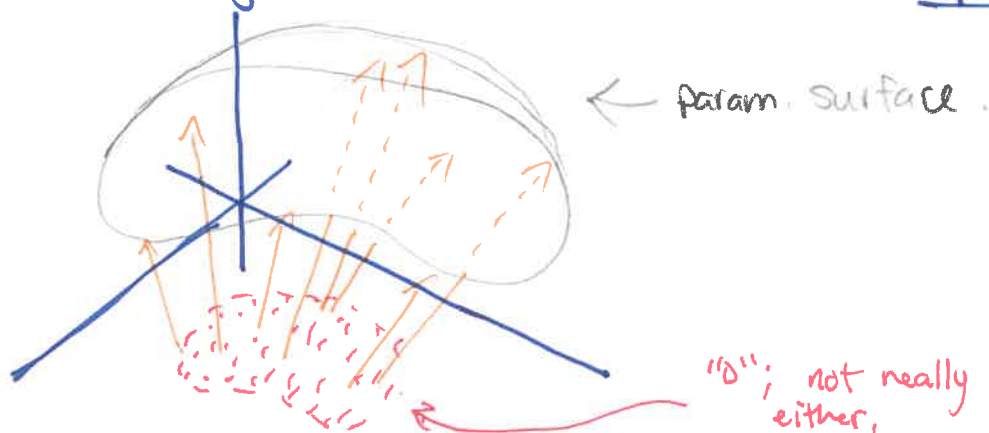


not really in the xy-plane, but a convenient visual tool.

Now, if we let the vector func.

\vec{r} have two parameters, we can get a 2D shape (i.e. a surface!)

• If $\vec{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$ is defined on a region D in the uv -plane, the set $\{x(u,v), y(u,v), z(u,v) \mid \in \mathbb{R}^3 \text{ as } (u,v) \text{ varies throughout } D\}$ is called a parametric surface.

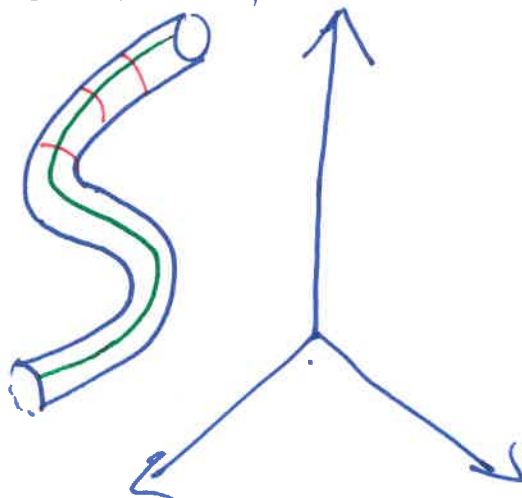


"D"; not really in xy-plane either.

Ex: ① $\vec{r}(u,v) = \langle 2\cos u, v, 2\sin u \rangle$
↳ Cylinder (see computer)

② $\vec{r}(u,v) = \langle (2+\sin v)\cos u, (2+\sin v)\sin u, u + \cos v \rangle$
↳ pasta noodle. (computer)

$u = \text{const}$
 $v = \text{const}$



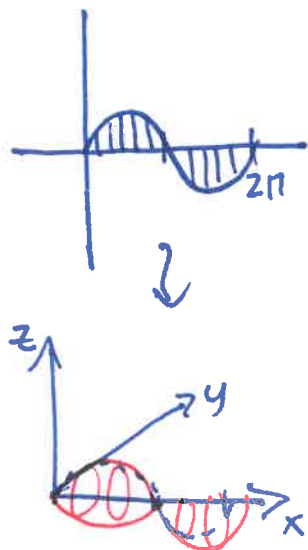
③ Surfaces of revolution

↳ Ex: Rotate $y=f(x)$ about x -axis ($f(x) \geq 0, a \leq x \leq b$).
 $\Rightarrow x=x \quad y=f(x)\cos\theta \quad z=f(x)\sin\theta$.

Ex: Rotate $y=\sin x, 0 \leq x \leq 2\pi$, about x -axis.

$\Rightarrow x=x \quad y=\sin x \cos\theta \quad z=\sin x \sin\theta$

↓
See computer



Note: Parametric Surfaces make
better computer graphics!

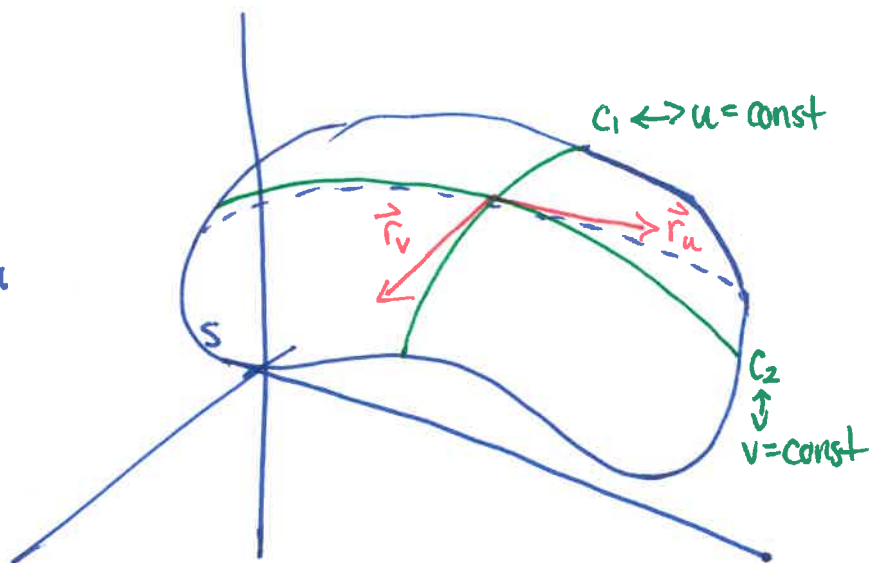
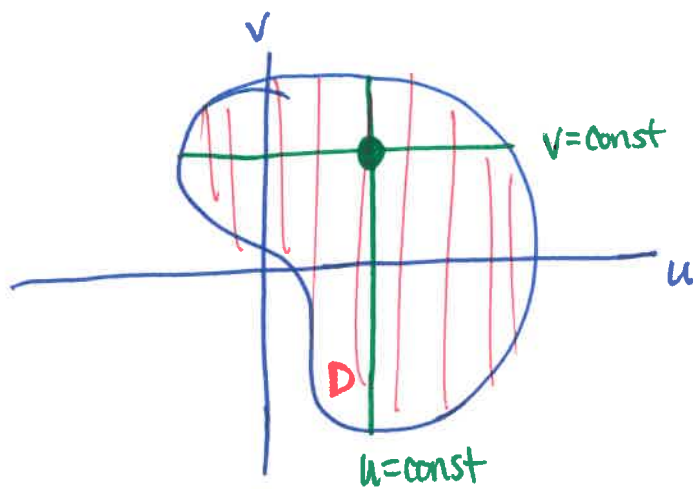
(see sphere ex on cpu)

Tangent Planes

Given $\vec{r}(u,v) = \langle x(u,v), y(u,v), z(u,v) \rangle$, let

$$\vec{r}_u = \left\langle \frac{\partial x}{\partial u}(u,v), \frac{\partial y}{\partial u}(u,v), \frac{\partial z}{\partial u}(u,v) \right\rangle$$

$$\vec{r}_v = \left\langle \frac{\partial x}{\partial v}(u,v), \frac{\partial y}{\partial v}(u,v), \frac{\partial z}{\partial v}(u,v) \right\rangle.$$



- Tangent plane exists at a pt if $\vec{r}_u \times \vec{r}_v \neq \vec{0}$ at that pt.

↳ If it exists, it is the plane containing \vec{r}_u & \vec{r}_v & normal to $\vec{r}_u \times \vec{r}_v$.

Ex: Find tan. plane @ (1,1,3) to surface $x=u^2, y=v^2, z=u+2v$.

- $\vec{r}_u = \langle 2u, 0, 1 \rangle$ & $\vec{r}_v = \langle 0, 2v, 2 \rangle \Rightarrow$ normal vec. is

$$\vec{r}_u \times \vec{r}_v = \langle -2v, -4u, 4uv \rangle.$$

@ pt $(u,v) = (1,1)$: $\langle -2, -4, 4 \rangle$.

- Plane is: $-2(x-1) - 4(y-1) + 4(z-3) = 0$.