Errata for Shocks and Rarefactions Arise in a Two-Phase Model with Logistic Growth

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Abstract

This errata is necessary to address a crucial type and to discuss a minor error. In equation (5), there is a missing derivative which can make reproduction of these results difficult to attain. Next, our particular choice of $\Gamma(t) = 0$ to produce this results in this paper are physically irrelevant. Instead, we make a choice of $\Gamma(t) = 1$, in which we see, similar results can be achieved as those produced in the paper.

1. The Two-Phase Model

This is the reduced two-phase model given in the original paper.

$$\frac{\partial}{\partial t}(\phi_1) + \frac{\partial}{\partial x}(u\phi_1) = G(\phi_1, 1 - \phi_1), \quad (1)$$

$$-\frac{\partial}{\partial t}(\phi_1) + \frac{\partial}{\partial x}(v(1-\phi_1)) = -G(\phi_1, 1-\phi_1), (2)$$

$$\mu_1(1-\phi_1)\frac{\partial}{\partial x}\left(\phi_1\frac{\partial}{\partial x}u\right) - \mu_2\phi_1\frac{\partial}{\partial x}\left((1-\phi)\frac{\partial}{\partial x}v\right) = Q$$
(3)

where

$$Q = \xi \phi_1 (1 - \phi_1) (u - v) + k_2 \phi \frac{\partial}{\partial x} \phi_1 (1 - \phi) (3\phi_1 - 2\phi_0)$$

The osmotic pressure function (not given explicitly in the original paper) takes the form $\psi(\phi_1) = k_2 \phi_1^2(\phi_1 - \phi_0)$, where ϕ_0 is a reference volume fraction.

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2. General Reduction

The transformation we found is

$$u(t,x) = \frac{\Gamma(t)}{\alpha} + f\left(x - \frac{1}{\alpha}\int\Gamma(t)dt\right),$$

$$v(t,x) = \frac{\Gamma(t)}{\alpha} + g\left(x - \frac{1}{\alpha}\int\Gamma(t)dt\right),$$

$$\phi_1(t,x) = m\left(x - \frac{1}{\alpha}\int\Gamma(t)dt\right),$$
(4)

where Γ , assumed to be smooth, is an arbitrary function of t, and α is an arbitrary constant. Applying the transformation given by (4) to (1-3) reduces the system to the ordinary differential equations given by

$$(mf)' - G = 0,$$

$$((1 - m)g)' + G = 0,$$

$$\mu_1(1 - m) (mf')' - \mu_2 m ((1 - m)g')'$$

$$-k_2(1 - m)m'(3m - 2\phi_0) - \xi m(1 - m)(f - g) = 0,$$
(5)
(6)

where m, f, and g are all functions of $r = x - \frac{1}{\alpha} \int \Gamma(t) dt$ that are to be determined.

3. Logistic Growth in an Inviscid System

Under this section we made the following case for $\Gamma(t) = 0$, but this particular choice trivializes the invariant surface condition. In other words, to derive the transformation (4), we need to solve the system

$$\alpha u_t + \Gamma(t)u_x = \frac{d}{dt}\Gamma(t), \tag{7}$$

$$\alpha v_t + \Gamma(t)v_x = \frac{d}{dt}\Gamma(t), \tag{8}$$

$$\alpha \phi_{1t} + \Gamma(t)\phi_{1x} = 0. \tag{9}$$

Instead, we present the case of $\Gamma(t) = 1$, and let $\alpha = 1000$. With these choices, the graphs remain virtually unchanged.

3.1.
$$\Gamma(t) = 1$$

For
$$u(\phi_1(x,0), 0) = \begin{cases} 0 & \text{if } x < 0\\ x & \text{if } 0 < x < .5\\ 0.5 & \text{if } x > .5, \end{cases}$$
(10)

we have



Figure 1: For initial conditions given by (10) (top), this shows the characteristic curves for growth given by $k_1 = 1$ (left) and $k_1 = 5$ (right), producing shocks. As growth increases, we see more rapid shockwaves with high frequencies, where as small growth is slow to produce shocks and have lower frequencies.



Figure 2: For initial conditions given by (11), the characteristic curves for growth given by $k_1 = 1$ (left) and $k_1 = 5$ (right) we see rarefactions. As growth increases, we see the loss of information between characteristics increases with wider rarefactions.